

ODE THEORY: C^1 -DEPENDENCE ON INITIAL DATA

ARICK SHAO

In this short note, we give a detailed proof of the C^1 -dependence on initial data for a family of solutions of a C^1 -system of ODEs. More specifically, we consider the following system,

$$(1) \quad x' = f(t, x),$$

where:

- $t \in \mathbb{R}$ is the independent variable.
- $x : I \rightarrow \mathbb{R}^n$ is the unknown, with $I \subseteq \mathbb{R}$ begin some interval containing 0.
- The function $f : \mathbb{R}_t \times \mathbb{R}_x^n \rightarrow \mathbb{R}^n$ defines the system of ODEs.

The main statement we wish to prove is the following:

Theorem 1. *Let $J \subseteq \mathbb{R}$ be a nonempty closed interval, and suppose $x : J_r \times [0, T]_t \rightarrow \mathbb{R}^n$ is a family of solutions—parametrised by $r \in J$ —of (1), that is,*

$$(2) \quad \partial_t x(r, t) = f(t, x(r, t)), \quad x(r, 0) = x_0(r),$$

with $x_0 : J \rightarrow \mathbb{R}^n$ being the corresponding family of initial data.

If f and x_0 are both C^1 , then the solution x is also C^1 (in both r and t).

Remark. *Since f is C^1 , then f is automatically both locally bounded and locally Lipschitz in x . By the standard existence and uniqueness result, each individual solution $x(r, \cdot)$ exists uniquely and is C^1 in t . Thus, the remaining task is to prove the same C^1 -regularity in r .*

C^0 -Dependence on Data. As warm-up, we first prove C^0 -dependence of the solution x on r . For this, we fix throughout $r, r_0 \in J$, and we set¹

$$y(t) := y(r, r_0; t) := x(r, t) - x(r_0, t).$$

Differentiating y and recalling (2) results in the identity

$$(3) \quad y'(t) = f(t, x(r, t)) - f(t, x(r_0, t)).$$

Integrating (3) and recalling $y(0) = x_0(r) - x_0(r_0)$, we see that

$$|y(t)| \leq |x_0(r) - x_0(r_0)| + \int_0^t |f(s, x(r, s)) - f(s, x(r_0, s))| ds.$$

Since the domain of x is compact, then by the local Lipschitz properties of f (due to f being C^1),

$$(4) \quad |y(t)| \leq |x_0(r) - x_0(r_0)| + L \int_0^t |x(r, s) - x(r_0, s)| ds = |x_0(r) - x_0(r_0)| + L \int_0^t |y(s)| ds.$$

Applying Gronwall's inequality to (4) yields

$$|x(r, t) - x(r_0, t)| = |y(t)| \leq |x_0(r) - x_0(r_0)| e^{tL}.$$

In particular, as $r \rightarrow r_0$, then $x(r, t) \rightarrow x(r_0, t)$, so that x is indeed continuous in r for each t .

¹For simplicity of notation, we suppress the dependence of y on r and r_0 .

r -Differentiability of x . The next step is to show that x is differentiable in the r -direction and to determine this derivative. The main idea is to note from (2) that

$$\partial_t \left[\frac{x(r, t) - x(r_0, t)}{r - r_0} \right] = \frac{f(t, x(r, t)) - f(t, x(r_0, t))}{r - r_0}$$

Taking a formal (and completely unrigorous) limit of the above as $r \rightarrow r_0$, we can guess that if $\partial_r x$ indeed exists, then it should satisfy the following system of ODEs:²

$$\partial_t(\partial_r x)(r_0, t) = \frac{d}{dr} f(t, x(r, t)) \Big|_{r=r_0} = \nabla_x f(t, x(r_0, t)) \cdot \partial_r x(r_0, t).$$

To be rigorous, we now work backwards: let A denote the solution of the initial value problem³

$$(5) \quad \partial_t A(t) = \nabla_x f(t, x(r_0, t)) \cdot A(t), \quad A(0) = x'_0(r_0).$$

(Since the system is linear, and since $\nabla_x f(t, x(r_0, t))$ is well-defined, $A(t)$ is guaranteed to exist on all of $[0, T]$.) Consider now the function $B : [0, T] \rightarrow \mathbb{R}^n$ given by

$$(6) \quad B(t) := \frac{x(r, t) - x(r_0, t)}{r - r_0} - A(t).$$

A direct computation using (5), (6), and the fundamental theorem of calculus yields

$$\begin{aligned} B'(t) &= \frac{1}{r - r_0} \int_0^1 \frac{d}{ds} [f(t, s \cdot x(r, t) + (1 - s) \cdot x(r_0, t))] ds - \nabla_x f(t, x(r_0, t)) \cdot A(t) \\ &= \int_0^1 \nabla_x f(t, s \cdot x(r, t) + (1 - s) \cdot x(r_0, t)) ds \cdot \frac{x(r, t) - x(r_0, t)}{r - r_0} - \nabla_x f(t, x(r_0, t)) \cdot A(t). \end{aligned}$$

A bit of algebraic manipulation then reveals that

$$(7) \quad B'(t) = C_1(t) \cdot B(t) + C_2(t) \cdot A(t),$$

where

$$(8) \quad \begin{aligned} C_1(t) &= \int_0^1 \nabla_x f(t, s \cdot x(r, t) + (1 - s) \cdot x(r_0, t)) ds, \\ C_2(t) &= \int_0^1 [\nabla_x f(t, s \cdot x(r, t) + (1 - s) \cdot x(r_0, t)) - \nabla_x f(t, x(r_0, t))] ds. \end{aligned}$$

Again, for notational brevity, we suppress the dependence on r and r_0 .

Since x is continuous, and since f is C^1 , then both C_1 , C_2 , and A are uniformly bounded:

$$(9) \quad \sup_{0 \leq t \leq T} [|A(t)| + |C_1(t)| + |C_2(t)|] \leq M.$$

Furthermore, since f is C^1 , we can also see that

$$(10) \quad \lim_{r \rightarrow r_0} \sup_{0 \leq t \leq T} |C_2(t)| = 0.$$

Thus, integrating (7) and recalling (9) and (10), we obtain the bound

$$(11) \quad \begin{aligned} |B(t)| &\leq |B(0)| + \int_0^t |C_2(s)| |A(s)| ds + \int_0^t |C_1(s)| |B(s)| ds \\ &\leq |B(0)| + TP \sup_{0 \leq t \leq T} |C_2(t)| + M \int_0^t |B(s)| ds, \end{aligned}$$

²Here, the $\nabla_x f$ is an $(n \times n)$ -matrix, so that the dot product $\nabla_x f \cdot \partial_r x$ is an n -vector.

³Again, we suppress the dependence of A on r and r_0 .

and applying the Gronwall inequality to (11) yields

$$(12) \quad |B(t)| \leq e^{tM} \left[|B(0)| + TM \sup_{0 \leq t \leq T} |C_2(t)| \right].$$

Note that as $r \rightarrow r_0$,

$$(13) \quad B(0) = \frac{x_0(r) - x_0(r_0)}{r - r_0} - x'_0(r_0) \rightarrow 0.$$

Combining (12) with (10) and (13), we conclude that $B(t) \rightarrow 0$ as $r \rightarrow r_0$ for each t . By the definition of $B(t)$, this implies that $\partial_r x(r_0, t)$ exists and is equal to $A(t)$.

C^1 -Dependence on Data. By showing that $\partial_r x(r_0, t)$ exists and is equal to this $A(t)$ in the preceding argument, we conclude that $\partial_r x$ itself solves a linear system of ODEs:

$$(14) \quad \partial_t(\partial_r x)(r, t) = \nabla_x f(t, x(r, t)) \cdot \partial_r x(r, t), \quad (\partial_r x)(r, 0) = x'_0(r).$$

This already implies that $\partial_r x$ is continuous with respect to t .

Integrating (14), we obtain the bound

$$(15) \quad \begin{aligned} |\partial_r x(r, t) - \partial_r x(r_0, t)| &\leq |x'_0(r) - x'_0(r_0)| \\ &\quad + \int_0^t |\nabla_x f(s, x(r, s)) \cdot \partial_r x(r, s) - \nabla_x f(s, x(r_0, s)) \cdot \partial_r x(r_0, s)| ds \\ &\leq |x'_0(r) - x'_0(r_0)| + \int_0^t |\nabla_x f(s, x(r, s)) - \nabla_x f(s, x(r_0, s))| |\partial_r x(r, s)| ds \\ &\quad + \int_0^t |\nabla_x f(s, x(r_0, s))| |\partial_r x(r, s) - \partial_r x(r_0, s)| ds. \end{aligned}$$

By Gronwall's inequality and various uniform bounds, (15) implies that

$$(16) \quad |\partial_r x(r, t) - \partial_r x(r_0, t)| \leq e^{Lt} \left[|x'_0(r) - x'_0(r_0)| + C \int_0^t |\nabla_x f(s, x(r, s)) - \nabla_x f(s, x(r_0, s))| ds \right]$$

for some constants $C, L > 0$. Since x_0 and f are C^1 , the terms within the brackets on the right-hand side of (16) vanish as $r \rightarrow r_0$. This proves the continuity of $\partial_r x$ with respect to r .